

# **DUBLIN CITY UNIVERSITY**

## ***Sample Paper***

<b>MODULE:</b> <i>(Title &amp; Code)</i>	Computer Graphics CA417
<b>COURSE:</b>	B.Sc. in Computer Applications (CASE) B.Sc. in Computer Applications (CAIS)
<b>YEAR:</b>	4
<b>EXAMINERS:</b>	Dr. David Sinclair
<b>TIME ALLOWED:</b>	2 Hours
<b>INSTRUCTIONS:</b>	Please answer 3 questions. All questions carry equal marks

**THE USE OF PROGRAMMABLE OR TEXT STORING  
CALCULATORS IS EXPRESSLY FORBIDDEN**

**Please note that where a candidate answers more than the required number of  
questions, the examiner will mark all questions attempted and then select the  
highest scoring ones.**

**PLEASE DO NOT TURN OVER THIS PAGE UNTIL YOU ARE  
INSTRUCTED TO DO SO**

### Question 1

- 1(a) What is the role of capabilities in Java3D? [5 marks]  
1(b) Describe the different geometry arrays in Java3D. [14 marks]  
1(c) Write a small Java3D program that defines a pyramid in a scene graph using an indexed geometry. [14 marks]

[Total marks: 33]

### Question 2

- 2(a) In *ray tracing*, what is an **eye ray**? [4 marks]  
2(b) Describe an efficient method for calculating the intersection of an eye ray and a sphere. Use a parametric representation of the eye ray. [10 marks]  
2(c) Write the pseudo-code for a recursive ray tracing algorithm. [15 marks]  
2(d) Classic optimisations used in visible surface determination cannot be used in recursive ray tracing. Why? [4 marks]

[Total marks: 33]

### Question 3

- 3(a) Describe the role of **clipping** in the graphics pipeline. [6 marks]  
3(b) Describe the Cohen-Sutherland clipping algorithm in two dimensions. [12 marks]  
3(c) Show how the Cohen-Sutherland algorithm can be extended to deal with normalised perspective projection in three dimensions. [10 marks]  
3(d) What is the key inefficiency of the Cohen-Sutherland algorithm? [5 marks]

[Total marks: 33]

### Question 4

- 4(a) Describe a vector cross-product in three dimensional space. [5 marks]  
4(b) Describe parallel and perspective projection. [6 marks]  
4(c) Calculate the transformation matrix for perspective projection where the view plane is defined by a its reference point  $[0,1,0]^T$  and its normal  $[0,0,1]^T$ . The viewing window is defined by minimum and maximum (u,v) values of (0,0) and (200,300) respectively. The viewing point is located at  $[-2,2,10]^T$  and its up-vector is  $[0,1,0]^T$ . The front and back clipping planes are  $z=2$  and  $z=-5$  respectively. [12 marks]  
4(d) Apply the transformation matrix derived in part (b) to a cube centred on the origin and whose side are of length 2. [10 marks]

[Total marks: 33]